

Process Control Trainer

37-100



Description

A heating element controlled by a thyristor circuit feeds heat into the airstream circulated by an axial fan along a polypropylene tube. A thermistor detector, which may be placed at one of three points along the tube length, senses the temperature at that point. The volume of air flow is controlled by varying the speed of the fan via a potentiometer. A change in setting represents a supply side disturbance and the effects are easily demonstrated. The detector output is amplified to provide both an indication of the measured temperature and a feedback signal for comparison with a set value derived from a separate control. A comparison of these signals generates a deviation signal which is applied to the heater control circuit such that the controlled condition is maintained at the desired value.

The variation of dynamic behaviour with loop gain can be studied with the variable gain facility (proportional band). By increasing the loop gain, oscillatory responses and finally instability are caused. Provision is made for the introduction of set value disturbances in the form of electrical inputs from a suitable function generator (e.g. Feedback FG601).

Many simple temperature control systems use two-step (ON/OFF) controls, which operate when the temperature is outside the controlled limits. A simple switch converts the 37-100 to this mode so that control accuracy and stability can be demonstrated. The effects of adjustments of overlap and maximum heater power can be studied. An external controller is available to enable the operation of compound control to be investigated. The three term controller module PID150Y provides variable controls for adjustment of proportional, integral and derivative terms.

An external +15V, 100 mA power supply is required for the PID150Y module.

Optional Accessories

Function Generator FG601 Electronic Wattmeter EW1604





Features

- For teaching the basic ideas of process control to technicians, process operators and control engineers
- A practical process in miniature
- Designed for the instruction of students at all levels
- Demonstrates closed and open-loop continuous control as well as two-step control
- Response times enables dynamic behaviour to be seen on oscilloscope or chart recorder
- The system exhibits thermal time constants and time transport lag
- Meters with side-by-side pointers indicate set and measured value

Distance/Velocity Lag

With the loop open a signal is applied to the controller. Either a step change from a switch on the panel or a signal from an external function generator. Distance/velocity lag (or transport lag) can be measured directly on an oscilloscope triggered by the applied signal.

Transfer Lag

The open-loop response to a step change can be measured directly on an oscilloscope. The shape of the curve is principally determined by the heater/air and detector/air time constants and an increase in air flow rate will be seen to produce a reduction in transfer lag.

Calibration

Monitoring points are available which enable the steady-state signal levels at different parts of the system to be measured.

Two-step Control

The two-step controller has overlap adjustable down to zero and means of controlling maximum heater power. The effect of overlap on the amplitude and frequency of temperature alternations can be demonstrated.

Proportional Control

With the loop closed the effect on offset of altering the proportional bandwidth can be observed by comparing the readings on the "set value" and "measured value" meters or by observing deviation directly on an oscilloscope. As proportional bandwidth is decreased offset is reduced until a point is reached at which the system becomes unstable.

System Response

A supply side disturbance can be produced by changing the inlet air flow, and a change in set value introduced either internally or externally. The response to a step function disturbance can be made under-damped, critically damped or over-damped by adjustment of proportional band.

Frequency Response

With the loop open and a sine wave signal applied to the input side, measurements of gain and phase are made over the frequency range 0.1 to 10 Hz. The use of Nyquist and Bode diagrams in the analysis of the result is discussed.





Specification

80 W Maximum heater power

Velocity flow range 1 – 10 ft/sec

(0.304 - 3.05 m/sec)Ambient to 80 degrees **Detector temperature range**

Heater/detector time constant 400 ms Typical distance – velocity lag 200 ms

Typical natural period 10 seconds

298 mm (11.75 inches) **Tube length**

Electrical input and output range Manual supplied Process Trainer 37-100

220 - 250 V or 100 - 120 V **Power requirements**

Dimensions and Weight Width: 520 mm Depth: 292 mm Height: 216 mm

Weight: 5.6 kg

50 or 60 Hz. 170 VA

+ 10 V

Tender Specification

Demonstrator to provide studies of basic control processes used in typical industrial applications. To provide the controls and metering required to demonstrate closed and open-loop continuous control and two-step control. To be compatible with comprehensive instruction manual of assignments and projects supplied on CD-ROM.

Ordering information

Process Trainer 37-100

Optional Accessories

Function Generator FG601 Electronic Wattmeter EW1604



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